



# **BASIC FEATURES**

- ☐ Multi-input and multi-range performance
- ☐ Large 20mm bright display (SR93)
- □ Readable from a distance and in a low light area
- □ 2-output heating and cooling control available
- ☐ RS232C or RS485 Interface (MODBUS / Shimaden) available
- ☐ Dust and splash proof front panel equivalent to IP66
- ☐ A wide selection of additional functions (optional) is available to suit various needs.

PID (output 1) + PID (output 2) Display RA (reverse action characteristic): Heating action Digital display: Measured value (PV)/7 segments red LED (OUT1) and cooling action (OUT2) DA (direct characteristic): 2-stage heating action Target set value (SV)/7 segments green LED 4 digits ±(0.3%FS + 1 digit) Contact/1a 240V AC 2A (resistive load) Type of control/rating: 1.2A (inductive load) Display accuracy: SSR drive voltage/12V±1.5V DC (Common to Output 1 and 2): Excluding reference contact temperature (Maximum load current 30mA) compensation accuracy of thermocouple Current/4~20mA DC (Maximum load input. resistance  $600\Omega$ ) Accuracy of readings lower than -100°C of Voltage/0~10V DC (Maximum load thermocouples K, T, U inputs is ±0.7%FS. current 2mA) Accuracy guarantee not applicable to Control output 1: approx. 0.0125% (1/8000) 400°C (752°F) and below of B Control output resolution: Control output 2: approx. 0.5% (1/200) thermocouple. Control output 1 Display accuracy maintaining range: Proportional band (P): OFF, 0.1~999.9% (ON-OFF action by OFF)  $23^{\circ}\text{C} \pm 5^{\circ}\text{C} (18\sim28^{\circ}\text{C})$ OFF, 1~6000 seconds Integral time (I): • Display resolution: Depends on measuring range (0.001, 0.01, (P or PD action by OFF) 0.1 and 1) Measured value display range: −10%~110% of measuring range Derivative time (D): OFF, 1~3600 seconds (P or PI action by OFF) 0.25 seconds Display updating cycle: OFF, 0.01~1.00 Set value function: 7 type, LED lamp display Action display/color: ON-OFF hysteresis: 1~999 units (Effective when P=OFF) Control output (OUT1, OUT2)/Green Event (EV1, EV2)/Orange Manual reset: -50.0~50.0% (Effective when I=OFF) Auto tuning/Green Higher/lower limit output limiter: Lower limit 0.0~99.9%, higher limit 0.1~100.0% (Lower limit value < Higher Manual control output (MAN)/Green limit value) Set value bias, communication (SB/COM)/Green Proportional cycle: 1~120 seconds (for contact and SSR drive ■ Setting voltage output) Control output 2 (option) By operating 4 keys (②, ▼, ▲ Setting method: Proportional band (P): OFF, 0.1~999.9% and (ENT) on the (ON-OFF action by OFF) front panel OFF, 1~6000 seconds Integral time (I): Target value setting range: Same as measuring range (within setting (P or PD action by OFF) limiter) OFF, 1~3600 seconds Derivative time (D): Individual setting for higher and lower • Setting limiter: (P or PI action by OFF) limits, any value is selectable within OFF. 0.01~1.00 Set value function: measuring range (Lower limit ON-OFF hysteresis: 1~999 units (Effective when P=OFF) value<Higher limit value) Dead band: -1999~5000 units (Overlap with a negative ■ Input value) Selectable from multiple (TC, Pt, mV), • Type of input: Higher/lower limit output limiter: Lower limit 0.0~99.9%, higher limit voltage (V) and current (mA) 0.1~100.0% (Lower limit value < Higher B, R, S, K, E, J, T, N, PL II, Wre5-26 {U, L • Thermocouple: limit value) (DIN 43710)} Proportional cycle: 1~120 seconds (for contact and SSR drive 500k**Ω** minimum Input impedance: voltage output) External resistance tolerance: 100Ω maximum Manual control Burnout function: Standard feature (up scale) 0.0~100.0% Output setting range: Reference junction compensation accuracy: Setting resolution: 0.1% ± 1°C (within the accuracy maintaining Manual ↔ auto switching: Balanceless bumpless (within proportional range  $(23 \pm 5^{\circ}C)$ range) ± 2°C (between 5 and 45°C of ambient OFF, 1~100 seconds Soft start: temperature) SV value in execution AT point: • R.T.D.: Pt100/JPt100, 3-wire type Control output characteristic: RA (reverse action characteristic)/DA Normal current: 0.25 mA (direct action characteristic) switching by  $5\Omega$  maximum/wire (3 lead wires should Lead wire tolerance: front key or communication have the same resistance.) With 2 outputs: RA (heating/cooling)/DA (2 stage heating)  $-10\sim10, 0\sim10, 0\sim20, 0\sim50, 10\sim50,$ Voltage mV: Contact output isolated from all. Isolation: 0~100mv DC Analog output not insulated from SSR drive -1~1, 0~1, 0~2, 0~5, 1~5, 0~10V voltage, current and voltage but insulated Input impedance: 500kΩ minimum from others. (In case another output is also Current mA: 0~20, 4~20mA DC SSR drive voltage, current or voltage, 250Ω Receiving impedance: two outputs are not insulated from Input scaling function: Scaling possible for voltage (mV, V) or each other.) current (mA) input ■ Event output (option) -1999~9999 counts Scaling range: Number of event points: 2 points of EV1 and EV2 10~5000 counts Span: Selectable from the following 9 types for Types: Position of decimal point: None, 1, 2 and 3 digits on the right of EV1 and EV2: decimal point oFF: No selection Sampling cycle: 0.25 seconds Ha: Higher limit deviation • PV bias: -1999~2000 units ∠ d: Lower limit deviation • PV filter: 0~100 seconds □ d: Outside higher/lower limit deviations • Isolation: Control input not insulated from system, set Within higher/lower limit deviations value bias, and CT input but insulated from *H***A**: Higher limit absolute value others LA: Lower lim
50: Scaleover Lower limit absolute value ■ Control Control mode **川**ら: Heater break/loop alarm With 1 output: Expert PID control with auto tuning function

Event setting range:

RA (reverse action characteristic): Heating action

DA (direct action characteristic): Cooling action

With 2 outputs: Expert PID control with auto tuning function +

PID control

Absolute values (both higher limit and

Deviations (both higher limit and lower

lower limit): Within measuring range

limit): -1999~2000 units

Higher/lower limit deviations

SR94: Approximately 240 g

(within/outside): 0~2000 units Data format: 8E1, 8E2, 8N1, 8N2 • Event action: ON-OFF action Control code: None 1~999 units Hysteresis: Error check: CRC-16 Standby action: Selectable from the following 4 types 03H, 06H (Hex) Function code: EV1 and EV2: Without standby action. 1) 03H, read data 2 Standby when power is applied. 2) 06H, write data 3 Standby when power is applied and when SV value in execution is changed. • Isolation: Communication signals insulated from system, each input and each output. 4 Control mode without standby action (No ■ Analog output (option) alarm is output at the time of abnormal • Number of output points: point input). Type of analog output: Selectable from measured value, target Contact (1a  $\times$  2 points common)/240V AC Output type/rating: value (SV in execution), control output 1 1A (resistive load) and control output 2. Output updating cycle: 0.25 seconds Output signal/rating: 4~20mA DC/Maximum load resistance 300Ω ■ Heater break/heater loop alarm (option) 0~10V DC/Maximum load current 2mA Heater break/loop detection only for OUT1 (Selectable when output  $0{\sim}10mV$  DC/Output resistance  $10\Omega$ type is contact or SSR drive voltage) Output scaling: Measured value, target value: Within Current capacity: 30A or 50A to be designated when CT is measuring range (inversed scaling possible) ordered. Control output 1 and 2 0.0~100.0% Alarm action: Heater current is detected by external CT (inversed scaling possible) provided as an accessory. ±0.3% FS (with respect to displayed value) Output accuracy: When heater break is detected while control Output resolution: Approx. 0.01% (1/10000) output is ON=Alarm output ON Output updating cycle: 0.25 seconds When heater loop alarm is detected while Isolation: Analog output insulated from system and control output is OFF=Alarm output ON inputs but not insulated from control output OFF, 0.1~50.0A (Alarm action is stopped Current setting range: except contact output. by setting OFF) ■ General specifications Setting resolution: Non-volatile memory (EEPROM) Data storage: • Environmental conditions for instrument operation: Current display range: 0.0~55.0A  $\pm 2.0$ A (Sine wave at 50Hz) Display accuracy -10-50 °C Temperature: 0.25 seconds (every 0.5 seconds) common 90% RH or less (no dew condensation) Minimum time to identify action: Humidity: to ON and OFF Height: 2000m from the sea level or lower Alarm retention mode: Selectable from lock (to retain) and real Category: (not to retain). Degree of pollution: Standby action: Selectable from without (OFF) and with -20-65 °C Storage temperature: (ON). Either 100-240V AC±10% 50/60Hz or Supply voltage: Sampling cycle: 0.5 seconds 24V AC/DC±10% to be designated. SR91: 100-240VAC 11VA maximum for AC; 6W for DC 24V; 7VA for AC 24V Isolation: CT input not insulated from system and • Power consumption: other inputs but insulated from the others. ■ Set value bias/DI (option) SR92, SR93 and SR94: 100-240VAC Number of input points: 1 point 15VA maximum for AC; 8W for DC Setting range: -1999–5000 units 24V; 9VA for AC 24V Non-voltage contact or open collector (level Action input: • Input/noise removal ratio: 50 dB or higher in normal mode (50/60 Hz) action) about 5V DC, 1mA maximum 130 dB or higher in common mode Minimum level retention time: 0.15 seconds (50/60 Hz)Safety: IEC1010 and EN61010-1 DI types: 1) None Applicable standards: 2) SB; set value bias EMC: EN61326 3) STBY; standby RoHS compliance: EN50581 Between input/output terminals and power terminal 500V DC 20M $\Omega$  or above; 4) ACT; control action characteristics Insulation resistance: Action input not insulated from system and • Isolation: other inputs but insulated from others Between input/output terminals and ■ Communication function (option) protective conductor terminal 500V DC 20MΩ or above Type of communication: RS-232C, RS-485 RS-232C: 3-line type half duplex system Communication system: • Dielectric strength: Between input/output terminals and power : 2-line type half duplex system RS-485 terminal 2300V AC 1 minute; Between (RS-485 is of half-duplex multi-drop (bus) power terminal and protective conductor system) terminal 1500V AC 1 minute Communication distance: RS-232C: The longest: 15 m Only front panel has dust-proof and drip-• Protective structure: RS-485 : The longest: 500 m (depending on proof structure equivalent to IP66. PPO resin molding (equivalent to UL94V-1) Material of case: conditions) Number of connectable instruments RS-232: 1, RS-485: up to 31 External dimensions: Start-stop synchronization system SR91: H48 × W48 × D111 (Panel depth: 100) mm Synchronization system: SR92: H72 × W72 × D111 (Panel depth: 100) mm 1200, 2400, 4800, 9600, 19200 bps Communication speed: SR93: H96 × W96 × D111 (Panel depth: 100) mm Communication address: 1~255 SR94: H96 × W48 × D111 (Panel depth: 100) mm ● Communication delay time: 1~100 (× 0.512 msec) • Mounting: Communication memory mode: EEP/RAM/r\_E Push-in panel (one-touch mount) Shimaden standard protocol Communication protocol(1): Panel thickness: 1.0-4.0 mm 7E1, 7E2, 7N1, 7N2, 8E1, 8E2, 8N1, 8N2 SR91: H45 × W45 mm Data format: • Panel cutout: SR92: H68 × W68 mm SR93: H92 × W92 mm STX\_ETX\_CR, @\_:\_CR Control code: Communication BCC: Add, Add two's cmp, XOR, None SR94: H92 × W45 mm Communication code: ASCII code MODBUS ASCII mode 7E1, 7E2, 7N1, 7N2 SR91: Approximately 170 g Communication protocol(2): • Weight: SR92: Approximately 280 g Data format: **CRLF** SR93: Approximately 330 g Control code:

LRC check

• Communication protocol(3): MODBUS RTU mode

03H, 06H (Hex) 1) 03H, read data 2) 06H, write data

Error check

Function code:

Open collector input rating: approx. 5V/1mA max.  O Without	ITEM CODE								SPECIFICATIONS					
Note	SERIES	SR91-	SR91-						MPU-Based Auto-Tuning PID Digital Controller, DIN H48 × W48 × D110mm					
Voltage: -10-10, 0-10, 0-20, 0-50, 1-0-50, 0-100mV DC   10-50, 0-100mV DC   10-5000   10-500   10-500   10-500   10-500   10-500   10-500   10-5000   10-500   10-500   10-500   10-500   10-5000   10-500   10-				8 Multi innu		ılti innut			R.T.D.: Pt100Ω /JPt100Ω					
Current (mA): 0-20, 4-20mA DC   Range: -1999-9999   Span: 10-5000   Note: Inverse scaling is not possible   Span: 10-5000   Note: Inverse scaling   Span: 10-5000				'''	p	u.			_	_				
A	INPLIT								10~50, 0~100mV DC	· ·				
Voltage (V): -11, 0-1, 0-2, 0-5,   sin not possible    -5, 0-10V DC   sin not pos			4						Current (mA): 0~20, 4~20mA DC	Range: -1999~9999				
V									Receiving impedance: $250\Omega$	•				
V-   Contact: 1a, Contact capacity: 240V AC 2.5A/resistive load   Proportional cycle: 1-120 sec.			6											
Proportional cycle: 1~120 sec.									•	·				
CONTROL OUTPUT (1)				Y-						A/resistive load				
CONTROL OUTPUT (1)   P-														
P				I-										
P	CONTROL	OUTPUT	(1)											
V-   Voltage: 0-10V DC   Load current: 2mA max.			( · )	P-					<u> </u>	<b>C.</b>				
POWER SUPPLY   90-   100-240V AC±10%, 50/60Hz				·					Proportional cycle: 1~120 sec.					
POWER SUPPLY				V-					Voltage: 0~10V DC					
POWER SUPPLY   08-   24V AC/DC±10%, 50/60Hz									Load current: 2mA max.					
24V AC/DC±10%, 50/60Hz	POWER S	I IPPI Y							100~240V AC±10%, 50/60Hz					
Control Output (2)   1   Contact output (2a) Ev1, Ev2: 240V AC 1A/resistive load	TOWEITO				-80									
Control output (2)  Proportional cycle: 1~120 sec.  United Proportional cycle: 1~120 sec.  Control output (2)  Proportional cycle: 1~120 sec.  Voltage: 0~10V DC Load current: 2mA max.  Proportional cycle: 1~120 sec.  Voltage: 0~10V DC Load current: 2mA max.  Current setting range: 0.1~30.0A (with CT 30A)  Analog output  Analog output  Analog output  Communication  SV Bias / DI  Note: Avaialble only when control output (1) is Y or P and when event output is selected.  Voltage: 0~10mV DC, Output resistance: 10Ω  Current: 4~20mA DC, Load current: 2mA max.  Communication  SV Bias / DI  Note: Avaialble only when control output (1) is Y or P and when event output is selected.  Voltage: 0~10mV DC, Output resistance: 10Ω  Analog output  SV Bias / DI  Note: Avaialble only when control output (1) is Y or P and when event output is selected.  Voltage: 0~10mV DC, Load current: 2mA max.  Communication  SV Bias / DI  Note: Avaialble only when control output (1) is Y or P and when event output is selected.  Voltage: 0~10mV DC, Output resistance: 10Ω  Analog output  SV Bias / DI  Note: Avaialble only when control output (1) is Y or P and when event output is selected.  Voltage: 0~10mV DC, Load current: 2mA max.  Communication  SV Bias / DI  Note: Avaialble only when control output (1) is Y or P and when event output is selected.  Voltage: 0~10mV DC, Load current: 2mA max.  Communication  SV Bias / DI  Note: Avaialble only when control output (1) is Y or P and when event output is selected.  Voltage: 0~10mV DC, Doutput resistance: 10Ω  Analog output  Output is selected.  Voltage: 0~10mV DC, Doutput resistance: 10Ω  Figure 1. The put is the proposal output is selected.  Voltage: 0~10mV DC, Doutput resistance: 10Ω  Doutput is selected.  Voltage: 0~10mV DC, Doutput resistance: 10Ω  Analog output is selected.  Output is selected.	EVENT O	ITPLIT (OP	TIO	NI)					None					
Control output (2)   Y   Contact: 1a, Contact capacity: 240V AC 2.5A/resistive load Proportional cycle: 1~120 sec.   I   Current: 4~20mA DC   Load resistance: 600Ω max.   SSR drive voltage: 12±1.5V DC/30mA max.   Proportional cycle: 1~120 sec.   V   Voltage: 0~10V DC   Load current: 2mA max.   Note: Avaialble only when control output (1) is Y or P and when event output is selected.   Analog output   4   Current: 4~20mA DC, Load resistance: 300Ω max.   SV Oltage: 0~10mV DC, Output resistance: 10Ω   Analog output   4   Current: 4~20mA DC, Load resistance: 300Ω max.   Communication   SV Bias / DI   8   DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector input rating: approx. 5V/1mA max.   O   Without   Witho	LVLINI O	10) 10 110		11)		1			Contact output (2a) Ev1, Ev2: 240V AC 1A/r	resistive load				
Control output (2)   Proportional cycle: 1~120 sec.   Current: 4~20mA DC   Load resistance: 600Ω max.   Proportional cycle: 1~120 sec.   Voltage: 0~10V DC   Load current: 2mA max.   Note: Available only when control output (1) is Y or P and when event output is selected.   Voltage: 0~10W DC, Load current: 2mA max.   Current: 4~20mA DC, Load resistance: 10Ω   Analog output   4   Current: 4~20mA DC, Load resistance: 300Ω max.   Communication   5   RS-485 (Shimaden standard protocol / MODBUS (RTU / ASCII))   SV Bias / DI   8   DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector input rating: approx. 5V/1mA max.   O Without   DC   Without   DC   Without   DC   Without   DC   DC   DC   DC   DC   DC   DC   D							N		None					
Control output (2)   Control output (2)   Proportional cycle: 1~120 sec.     Current: 4~20mA DC							v		Contact: 1a, Contact capacity: 240V AC 2.5/	A/resistive load				
Control output (2)    Control output (2)							•		·					
Control output (2)  P   SSR drive voltage: 12±1.5V DC/30mA max. Proportional cycle: 1~120 sec.  V   Voltage: 0~10V DC Load current: 2mA max.    Current setting range: 0.1~30.0A (with CT 30A)   Note: Available only when control output (1) is Y or P and when event output is selected.    Analog output   Current: 4~20mA DC, Load resistance: 10Ω   Analog output   Current: 4~20mA DC, Load current: 2mA max.   Communication   SV Bias / DI   8   DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector input rating: approx. 5V/1mA max.    DEMARKS   DI   Without   DEMARKS   D									Current: 4~20mA DC					
P   SSR drive voltage: 12±1.5V DC/30mA max.   Proportional cycle: 1~120 sec.   Voltage: 0~10V DC   Load current: 2mA max.		Contro	l out	nut (2	•									
Proportional cycle: 1~120 sec.  Voltage: 0~10V DC Load current: 2mA max.  1 Current setting range: 0.1~30.0A (with CT 30A)  Heater break alarm  2 Current setting range: 0.1~50.0A (with CT 50A)  Analog output  3 Voltage: 0~10mV DC, Output resistance: 10Ω  4 Current: 4~20mA DC, Load resistance: 300Ω max.  6 Voltage: 0~10V DC, Load current: 2mA max.  Communication  5 RS-485 (Shimaden standard protocol / MODBUS (RTU / ASCII))  SV Bias / DI  8 DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector input rating: approx. 5V/1mA max.		Contro	· ou	. , ,			P							
OPTION       Load current: 2mA max.         Heater break alarm       1 Current setting range: 0.1~30.0A (with CT 30A)       Note: Avaialble only when control output (1) is Y or P and when event output is Selected.         Analog output       3 Voltage: 0~10mV DC, Output resistance: 10Ω         Analog output       4 Current: 4~20mA DC, Load resistance: 300Ω max.         6 Voltage: 0~10V DC, Load current: 2mA max.         Communication       5 RS-485 (Shimaden standard protocol / MODBUS (RTU / ASCII))         SV Bias / DI       8 DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector input rating: approx. 5V/1mA max.         DEMARKS									· · · · · · · · · · · · · · · · · · ·					
Detail of the setting range: 0.1~30.0A (with CT 30A)   Note: Avaiable only when control output (1) is Y or P and when event output is selected.							v		Voltage: 0~10V DC					
Heater break alarm  2	OPTION						v		Load current: 2mA max.					
Heater break alarm  2							1		Current setting range: 0.1~30.0A (with CT 3)	Note: Avaialble only				
Current setting range: 0.1~50.0A (with CT 50A)   is Y or P and when event output is selected.		Heater	hre	ak ala	ak alarm		alarm		alarm		'		Current Setting range. 6.1 66.67 (with 61 61	when control output (1)
Analog output  4		Treater break a		an aic	ak alalili						Current setting range: 0.1~50.0A (with CT 5	()A)		
6 Voltage: 0~10V DC, Load current: 2mA max.  Communication 5 RS-485 (Shimaden standard protocol / MODBUS (RTU / ASCII))  SV Bias / DI 8 DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector input rating: approx. 5V/1mA max.  0 Without	Analog						3		l '					
Communication 5 RS-485 (Shimaden standard protocol / MODBUS (RTU / ASCII))  SV Bias / DI 8 DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector inp Open collector input rating: approx. 5V/1mA max.  0 Without			out	put			4		Current: 4~20mA DC, Load resistance: 3000	Ω max.				
SV Bias / DI  8 DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector inp Open collector input rating: approx. 5V/1mA max.  0 Without				• •					Voltage: 0~10V DC, Load current: 2mA max.					
Open collector input rating: approx. 5V/1mA max.  O Without					5		RS-485 (Shimaden standard protocol / MODBUS (RTU / ASCII))							
Open collector input rating: approx. 5V/1mA max.  O Without		CV/ Piece / DI						DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector input						
DEMADKS	SV Blas / DI			8										
	DEMARKS			0										
9 With (Please consult before ordering.)	REMARKS 9					9	With (Please consult before ordering.)							

### Note:

When you purchase a two-output type controller and use it in a one output capacity, larger overshooting or undershooting may happen as a result of integral operation. Therefore, we recommend you to choose a one-output type.

The cause of the above-mentioned problem is that the positional relationship between the proportional band (PB) and the set value (SV) of a one-output type controller differs from that of a two-output type.

ITEM			C	ODE				SPECIFICATIONS				
SERIES	SR92-							MPU-Based Auto-Tuning PID Digital Controller, DIN H72 × W72 × D110mm				
			М	ulti input				Thermocouple: B, R, S, K, E, J, T, N, PLII, Wre5-26 {U, L (DIN 43710)} R.T.D.: Pt100 $\Omega$ /JPt100 $\Omega$ Voltage (mV): -10~10, 0~10, 0~20,				
INPUT									caling Possible			
"" " "		4							ange: -1999~9999			
								<u> </u>	pan: 10~5000			
		6							ote: Inverse scaling			
								0~10V DC Input resistance: 500kΩ min.	is not possible.			
			Y-					Contact: 1a, Contact capacity: 240V AC 2A/resisti	ve load			
								Proportional cycle: 1~120 sec.  Current: 4~20mA DC				
			I-					Load resistance: 600Ω max.				
CONTRO	OUTPUT (	(1)						SSR drive voltage: 12V±1.5V DC/30mA max.				
			P-					Proportional cycle: 1~120 sec.				
			V-					Voltage: 0~10V DC				
			V-					Load current: 2mA max.				
				N-				None				
				Y-				Contact: 1a, Contact capacity: 240V AC 2A/resistive load				
				1-				Proportional cycle: 1~120 sec.				
CONTROL	OUTPUT (	(2)		1-				Current: 4~20mA DC				
(OPTION)	- 0011 01 (	(_)						Load resistance: 600Ω max. (RA when shipped)				
,			P-					SSR drive voltage: 12V±1.5V DC/30mA max.				
								Proportional cycle: 1~120 sec.				
				V-				Voltage: 0~10V DC				
				90-	1			Load current: 2mA max.				
POWER S	UPPLY			08-				100V~240V AC±10%, 50/60Hz 24V AC/DC±10%, 50/60Hz				
				00-	0			None				
								Event output (2a) Ev1, Ev2				
					1			Contact capacity: 240V AC 1A/resistive load				
EVENT O	JTPUT/ BREAK ALA	RΜ	(OF	PTION)	2			Event output (Ev1) + Heater break alarm (with CT30	A) Note: Available only when control output (1)			
					3			Event output (Ev1) + Heater break alarm (with CT50	A) is Y or P is selected.			
						)		None				
ANALOG	ANALOG OUTPUT (OPTION)							Voltage: 0~10mV DC, Output resistance: 10Ω				
AINALOG	` ´					4		Current: 4~20mA DC, Load resistance: 300Ω max.				
6								Voltage: 0~10V DC, Load current: 2mA max.				
0								None				
5								RS-485 (Shimaden standard protocol / MODBUS (RTU / ASCII))				
COMMUNICATION OR SV Bias/DI (OPTION) 7								RS-232C (Shimaden standard protocol / MODBUS (RTU / ASCII))				
	8							DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector input				
	0						0	Open collector input rating: approx. 5V/1mA max.				
REMARKS	REMARKS 0							Without With (Please consult before ordering.)				
9							9	With (Please consult before ordering.)				

### Note:

When you purchase a two-output type controller and use it in a one output capacity, larger overshooting or undershooting may happen as a result of integral operation. Therefore, we recommend you to choose a one-output type.

The cause of the above-mentioned problem is that the positional relationship between the proportional band (PB) and the set value (SV) of a one-output type controller differs from that of a two-output type.

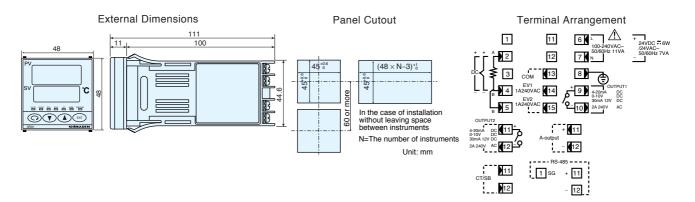
	ITEM CODE							SPECIFICATIONS				
SR SR	393-							MPU-Based Auto-Tuning PID Digital Controller, DIN H96 × W96 × D110mm				
SERIES SR	394-							MPU-Based Auto-Tuning PID Digital Controller, DIN H96 × W48 × D110mm				
							Thermocouple: B, R, S, K, E, J, T, N, PLII, Wre	[U, L (DIN 43710)}				
		N 414:					R.T.D.: Pt100Ω /JPt100Ω					
		8	Multi	Multi input				Voltage: -10~10, 0~10, 0~20,	For	voltage and current input:		
INDLIT								0~50, 10~50, 0~100mV DC	Scal	ling Possible		
INPUT		4						Current (mA): 0~20, 4~20mA DC Range: -1999~9999				
		4						Receiving impedance: 250Ω	Spa	~		
								Voltage (V): -1~1, 0~1, 0~2, 0~5, 0~10V DC Note: Inverse scaling				
		6						Voltage (V): $-1$ , $0$ , $0$ , $0$ , $0$ , $0$ , $0$ , $0$ , $0$				
			Y-					Contact: 1a, Contact capacity: 240V AC 2A/resi	istive	load		
								Proportional cycle: 1~120 sec.				
			I-					Current: 4~20mA DC				
CONTROL OUT	TPUT (	1)						Load resistance: 600Ω max.				
	`		P-					SSR drive voltage: 12V±1.5V DC/30mA max.				
								Proportional cycle: 1~120 sec.				
			V-					Voltage: 0~10V DC				
				NI I				Load current: 2mA max.				
				N-				None	- 12 1	11		
				Y-				Contact: 1a, Contact capacity: 240V AC 2A/resi	stive	load		
								Proportional cycle: 1~120 sec.  Current: 4~20mA DC				
CONTROL OUT	TPUT (2	2)		I-				Load resistance: 600Ω max.				
(OPTION)								SSR drive voltage: 12V±1.5V DC/30mA max.				
				P-				Proportional cycle: 1~120 sec.				
								Voltage: 0~10V DC				
				V-				Load current: 2mA max.				
					90-			100~240V AC±10%, 50/60Hz				
POWER SUPPL	LY			_	08-			24V AC/DC±10%, 50/60Hz				
						0		None				
								Event output (2a) Ev1, Ev2				
						1		Contact capacity: 240V AC 1A/resistive load				
EVENT OUTPU HEATER BREA		ВM	(OPTI	ION)		,			204)	Note: Available only		
TILATEN BILLA		I LIVI	(01 11	iOiv)		2		Event output (Ev1) + Heater break alarm (with CT3	30A)	when control output (1)		
						3		Event output (Ev1) + Heater break alarm (with CT	50A)	is Y or P is selected.		
						00		None				
						30		Voltage: 0~10mV DC, Output resistance: 10Ω				
	Anal	og c	output					Current: 4~20mA DC, Load resistance: 300Ω max.				
						60		Voltage: 0~10V DC, Load current: 2mA max.				
	C) / F	1:	/ DI			00		DI (set value bias, STBY, or ACT) 1 point, Non-voltage contact or Open collector input				
	SV Bias / DI			08		Open collector input rating: approx. 5V/1mA max.						
OPTION  Analog output + SV Bias / DI				20		Voltage: 0~10mV DC, Output resistance: 10Ω						
			38					DI (set value bias, STBY, or ACT) 1 point				
								Current: 4~20mA DC, Load resistance: 300Ω max.				
			/ DI					DI (set value bias, STBY, or ACT) 1 point				
				68		Voltage: 0~10V DC, Load current: 2mA max.						
						DI (set value bias, STBY, or ACT) 1 point						
Communication					05	_	RS-485 (Shimaden standard protocol / MODBUS (RTU / ASCII))					
07						07		RS-232C (Shimaden standard protocol / MODBUS (RTU / ASCII))				
REMARKS							0	Without				
I ILIVIAI IIIO							9	With (Please consult before ordering.)				

### Note:

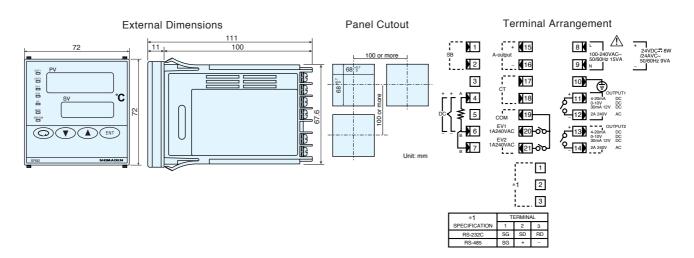
When you purchase a two-output type controller and use it in a one output capacity, larger overshooting or undershooting may happen as a result of integral operation. Therefore, we recommend you to choose a one-output type.

The cause of the above-mentioned problem is that the positional relationship between the proportional band (PB) and the set value (SV) of a one-output type controller differs from that of a two-output type.

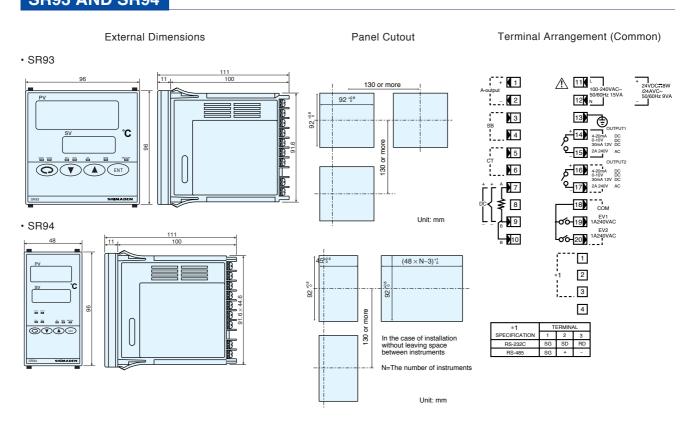
SR91 Series SR90



# **SR92**



# SR93 AND SR94



	Input 7	Гуре		Code	Measu	ring	range (°		Meas	uring	range (	(°F)
			*1	01	0	$\sim$	1800	°C	0	$\sim$	3300	°F
		R		02	0	$\sim$		°C	0	$\sim$	3100	°F
		S		03	0	$\sim$		°C	0	$\sim$	3100	°F
		K		04 *2	-199.9	$\sim$		°C	-300	$\sim$	750	°F
		K		05	0.0	$\sim$	800.0		0	$\sim$	1500	°F
		K		06	0	$\sim$		°C	0	$\sim$	2200	°F
		E		07	0	$\sim$		°C	0	$\sim$	1300	°F
		J		80	0	$\sim$		°C	0	$\sim$	1100	°F
	Thermo-	T		09 *2	-199.9	$\sim$		°C	-300	$\sim$	400	°F
	couple	N		10	0	$\sim$		°C	0	$\sim$	2300	°F
			*3	11	0	$\sim$		°C	0	$\sim$	2300	°F
		WRe5-26		12	0	$\sim$		ο̈	0	$\sim$	4200	°F
			*5	13 *2	-199.9	$\sim$		°C	-300	$\sim$	400	°F
l			*5	14	0	$\sim$		°C	0	$\sim$	1100	°F
Ιŧ			*6	15	10.0	$\sim$	350.0	K				
Multi-input			*7	16	0.0	$\sim$	350.0	K				
晋			*6	17	10	$\sim$	350	K				
≥		AuFe-Cr *7		18	0	$\sim$	350	K				
			L	31	-200	$\sim$	600	°C	-300	$\sim$	1100	°F
		Pt100	-	32	-100.0	$\sim$		°C	-150.0	$\sim$	200.0	
		11100		33	-50.0	$\sim$	50.0		-50.0	$\sim$	120.0	
	R.T.D.		_	34	0.0	$\sim$	200.0		0.0		400.0	
			-	35	-200	$\sim$		°C	-300	$\sim$	1000	°F
		JPt100	-	36	-100.0	$\sim$	100.0		-150.0	$\sim$	200.0	
			-	37	-50.0	$\sim$	50.0		-50.0	$\sim$	120.0	
			_	38	0.0	$\sim$	200.0	°C	0.0	~	400.0	) °F
		-10 ~ 10		71	Scaling possible							
	Valtana	0 ~ 10		72	Ocamig	poc	Sibic					
	Voltage	0 ~ 20	_	73	Owing to scaling function, any measuring range							
	(mV)	0 ~ 50		74								igo
		10 ~ 50		75	can be set within the following range.							
-		0 ~100	_	76	Scaling	ran	ne: -1999	9 to !	9999 co	unts		
		-1 ~ 1		81	Scaling range: -1999 to 9999 counts  Span: 10 to 5000 counts on condition of							
		0 ~ 1		82	lower side < higher side							
Vo	oltage (V)	0 ~ 2		83			IOWEI	Siut	- Iligii	ICI 310	ue .	
1	•	0 ~ 5 1 ~ 5		84								
		0 ~ 10		85								
$\vdash$			_	86								
Cu	rrent (mA)	0 ~ 20	_	91								
1	` '	4 ~ 20		92								

- Thermocouple:
  - B: Accuracy guarantee not applicable to 400°C (752°F) and below.

K, T, U: Accuracy guarantee not applicable to temperature below  $-100^{\circ}$ C  $\pm (0.7\% \text{ FS} + 1 \text{ digit})$ 

\*3 Thermocouple PLII: Platinel

\*4 Thermocouple Wre5-26: A product of Hoskins

\*5 Thermocouple

U. L: DIN 43710

\*6. Thermocouple K (Kelvin) accuracy

Temperature range External CJ Internal CJ

 $\begin{array}{l} 10.0 \sim & 30.0 \ \text{K} \pm (2.0\% \text{FS} + \text{[CJ error X 20] K} + 1 \text{K}) \\ 30.0 \sim & 70.0 \ \text{K} \pm (1.0\% \text{FS} + \text{[CJ error X} \quad 7] \ \text{K} + 1 \text{K}) \\ \end{array}$  $70.0 \sim 170.0 \text{ K} \pm (0.7\% \text{FS} + [\text{CJ error X} 3] \text{ K} + 1\text{K})$ 

 $170.0 \sim 270.0 \text{ K} \pm (0.5\%\text{FS} + [\text{CJ error X } 1.5] \text{ K} + 1\text{K})$ 270.0 ~ 350.0 K ±(0.3%FS + [CJ error X 1] K + 1K)

\*7. Thermocouple Metal-chromel (AuFe-Cr) (Kelvin) accuracy Temperature range External CJ Internal CJ

 $0.0 \sim 30.0 \text{ K} \pm (0.7\% \text{FS} + [\text{CJ error X} 3] \text{ K} + 1\text{K})$  $30.0 \sim 70.0 \text{ K} \pm (0.5\% \text{FS} + [\text{CJ error X } 1.5] \text{ K} + 1 \text{ K})$  $70.0 \sim 170.0 \text{ K} \pm (0.3\%FS + [CJ \text{ error X } 1.2] \text{ K} + 1 \text{ K})$ 170.0  $\sim$  280.0 K  $\pm$ (0.3%FS + [CJ error X 1] K + 1K)  $280.0 \sim 350.0 \text{ K} \pm (0.5\%\text{FS} + [\text{CJ error X} \ 1] \text{ K} + 1\text{K})$ 

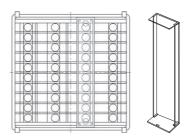
Unless otherwise specified, the measuring range will be set as listed below during the shipment from the factory.

Input	Specification/Rating	Measuring range
Multi-input	K thermocouple	0.0 ~ 800.0°C
Voltage (V)	0 ~ 10V DC	0.0 ~ 100.0
Current (mA)	4 ~ 20mA DC	0.0 ~ 100.0

## **TERMINAL COVER (AVAILABLE SEPARATELY)**

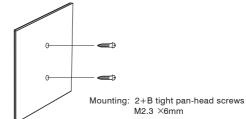
1	Model	Mounting
SR91	QCR001	One-touch mount
SR92	QCR002	One-touch mount
SR93	QCR003	One-touch mount

Material/Appearance: PVC/transparent Thickness: 1 mm



	Model	Mounting				
SR94	QCR004 (Individual mounting)	Plus screw, B tight, M2.3 × 6 - 2 pcs.				
SH94	QCR005 (Tight-lock coupling)	Plus screw, B tight, M2.3 × 6 - 4 pcs.				
M-4 D)/O/4 Thi-l 4						

Material/Appearance: PVC/transparent Thickness: 1 mm



### / Warning

• The SR90 series is designed for the control of temperature, humidity and other physical values of general industrial equipment. (It is not to be used for any purpose which regulates the prevention of serious effects on human life or safety.)

 If the possibility of loss or damage to your system or property as a result of failure of any part of the process exists, proper safety measures must be made before the instrument is put into use so as to prevent the occurrence of trouble.



(The contents of this brochure are subject to change without notice.)

**Temperature and Humidity Control Specialists** 

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